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Formula and data book

# Engineering 2025

# Formulas

Statics	
$c^2 = a^2 + b^2$	$F_H = F \cos \theta$
$\sin \theta = \frac{\text{opposite}}{\text{hypotenuse}}$	$F_V = F \sin \theta$
$\cos \theta = \frac{\text{adjacent}}{\text{hypotenuse}}$	$F_T = \sqrt{F_H^2 + F_V^2}$
$\tan \theta = \frac{\text{opposite}}{\text{adjacent}}$	$\tan \theta = \frac{F_V}{F_H}$
$M = Fd$	$M_T = M_1 + M_2 + M_3 + \dots$

Materials	
density = $\frac{\text{mass}}{\text{volume}}$	$E = \frac{FL}{A\Delta L} = \frac{\sigma}{\epsilon}$
$\sigma = \frac{F}{A}$	fos = $\frac{\text{yield stress}}{\text{allowable working stress}}$
$\epsilon = \frac{\Delta L}{L}$	UTS = $\frac{\text{maximum load}}{\text{original cross-sectional area}}$

Dynamics			
$F = ma$	$v_{av} = \frac{s}{t}$	$a = \frac{v-u}{t}$	$MA = \frac{F_L}{F_E}$
$VR = \frac{d_E}{d_L}$	$VR = \frac{\text{radius, diameter, circumference of driven pulley}}{\text{radius, diameter, circumference of driver pulley}}$		
$VR = \frac{\text{input speed}}{\text{output speed}}$	$GR \text{ or } VR \text{ for gears} = \frac{\text{radius, diameter, circumference or no.teeth of driven gear}}{\text{radius, diameter, circumference or no.teeth of driver gear}}$		
$W = Fs$	$GR \text{ or } VR \text{ for gears} = \frac{\text{angular movement of driven gear (effort)}}{\text{angular movement of driver gear (load)}}$		
$P = \frac{W}{t}$	$KE = \frac{1}{2}mv^2$	$PE = mgh$	$\eta = \frac{MA}{VR}$
$v = u + at$	$v^2 = u^2 + 2as$	$s = ut + \frac{1}{2}at^2$	$\mu_s = \tan \theta$
$F_f = \mu F_N$	$F_f = \mu_s F_N$	$F_f = \mu_k F_N$	

Electrical circuits		
$V = IR$	$P = VI$	$E = Pt$
$R_T = R_1 + R_2 + R_3 + \dots$	$V_T = V_1 + V_2 + V_3 + \dots$	$I_T = I_1 + I_2 + I_3 + \dots$
$\frac{1}{R_T} = \frac{1}{R_1} + \frac{1}{R_2} + \dots$	$\eta = \frac{P_{out}}{P_{in}} = \frac{\text{power output}}{\text{power input}}$	$\eta = \frac{E_{out}}{E_{in}} = \frac{\text{energy output}}{\text{energy input}}$








## Constant

Acceleration due to gravity
$g = 9.8 \text{ m s}^{-2}$

## Unit prefixes

Ratio to basic unit	Prefix	Abbreviation
$10^3$	kilo	k
$10^6$	mega	M
$10^9$	giga	G
$10^{12}$	tera	T
$10^{-1}$	deci	d
$10^{-2}$	centi	c
$10^{-3}$	milli	m

## Standard symbols

Electric circuits						
						

Logic gate		
